

THE STUDY ON THE PRIMARY SEALING WITH COAXIAL ROUND-SHAPED SURFACES

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Abstract: The paperwork studies the way of calculation of the interstitial pressure with Reynolds equation for the particular case of the primary sealing with coaxial round-shaped surfaces, one fixed and the other one rotating around Oz axis.

Keywords: Primary sealing, equation, Reynolds, coaxial

1. INTRODUCTION

Through this paperwork the particular case of primary sealing analyzed in xxxx is studied. Let's presume that S_1 and S_2 are coaxial round-shaped surfaces, S_1 is fixed, S_2 has rotational movement with angular speed ω around Oz axis (fig. 1).

For determining $H_1 = H(r, \theta, t)$, consider $M_1(r, \theta, z) \in S_1$. It's noticed that M_1 and N_1 have the same z .

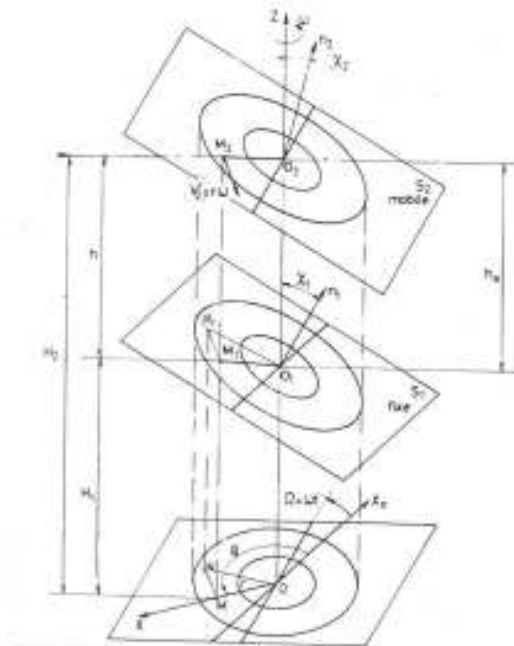


Figure 1.

$$z = NN_1 = OO_1 + O_1N_1 \cos NM_1O_1 = OO_1 + \frac{ON}{\sin NN_1O_1} \cos NM_1O_1 =$$

$$OO_1 + \frac{r \cos\left(\frac{\pi}{2} - \theta\right)}{\sin\left(\frac{\pi}{2} - \chi_1\right)} \cos\left(\frac{\pi}{2} - \chi_1\right) = OO_1 + R \sin \theta \operatorname{tg} \chi_1$$

Because χ_1 is low, it's approximated $\operatorname{tg} \chi_1 \approx \sin \chi_1 \approx \chi_1$, so:

$$H_1(r, \theta, t) = OO_1 + r \chi_1 \sin \theta \quad (1)$$

In a similar way for H_2 (replacing θ with $\theta - \omega t$ due to S_2 movement), results:

$$H_2(r, \theta, t) = OO_1 + h_0 + r \chi_2 \sin(\theta - \omega t) \quad (2)$$

Because the fluid is thick (viscous), it sticks to the surfaces, so

$$v_1^\theta = 0, \quad v_1^r = 0, \quad v_1^z = 0, \quad v_2^\theta = r\omega, \quad v_2^r = 0$$

We consider that h_0 is constant (uniform), so we could presume $v_2^z = 0$

The equation generalized Reynolds becomes:

$$\frac{\partial}{\partial r} \left[\frac{r}{\mu} (H_2 - H_1)^3 \frac{\partial p}{\partial r} \right] + \frac{\partial}{\partial \theta} \left[\frac{1}{\mu r} (H_2 - H_1)^3 \frac{\partial p}{\partial \theta} \right] = -6v_2^\theta \frac{\partial (H_1 + H_2)}{\partial \theta} \quad (3)$$

It's noted $h = H_2 - H_1$ and considered μ as constant. The equation (3) becomes:

$$\frac{\partial}{\partial r} \left(r h^3 \frac{\partial p}{\partial r} \right) + \frac{\partial}{\partial \theta} \left(\frac{h^3}{r} \frac{\partial p}{\partial \theta} \right) = 6\mu \omega r^2 [\chi_2 \cos(\theta - \omega t) + \chi_1 \cos \theta] \quad (4)$$

The equation (4) represents the Reynolds equation for the studied particular case. The admissible measures are introduced:

- the thickness $\bar{h} = \frac{h}{h_0}$
- the radius $\bar{r} = \frac{r}{R_e}; \quad \bar{r}_i = \frac{R_i}{R_e}$

- the relative tilt $\chi = \frac{\chi_1}{\chi_2}$
- the tilt-thickness film parameter $e_2 = R_e \frac{\chi_2}{h_0}$
- the rotor angular position $\Omega = \omega t$
- the pressure $\bar{p} = \frac{h_0^2}{6\mu R_e^2 \omega} p$.

Then:

- for $r \in [R_i, R_e]$ it gets $\bar{r} \in [\bar{r}_i, 1]$, and
- $\frac{\partial}{\partial r} = \frac{\partial}{\partial \bar{r}} \frac{\partial \bar{r}}{\partial r}$ so $\frac{\partial}{\partial r} = \frac{1}{R_e} \frac{\partial}{\partial \bar{r}}$;

The fluid thickness equation is:

$$h = H_2 - H_1 = h_0 + r\chi_2 \left[\sin(\theta - \omega t) - \frac{\chi_1}{\chi_2} \sin \theta \right]$$

Divide with h_0 and results:

$$\frac{h}{h_0} = 1 + \frac{r}{R_e} \frac{R_e \chi_2}{h_0} \left[\sin(\theta - \omega t) - \frac{\chi_1}{\chi_2} \sin \theta \right],$$

so:

$$\bar{h} = 1 + \bar{r} e_2 [\sin(\theta - \Omega) - \chi \sin \theta] \quad (5)$$

The Equation (4) is re-written:

$$\begin{aligned} & \frac{1}{R_e} \frac{\partial}{\partial \bar{r}} \left[\bar{r} R_e (\bar{h} h_0)^3 \frac{1}{R_e} \frac{\partial}{\partial \bar{r}} \left(\frac{6\mu R_e^2 \omega}{h_0^2} \bar{p} \right) \right] + \frac{\partial}{\partial \theta} \left[\frac{(h_0 \bar{h})^3}{R_e \bar{r}} \frac{\partial}{\partial \theta} \left(\frac{6\mu R_e^2 \omega}{h_0^2} \bar{p} \right) \right] = \\ & = -6\mu \omega (\bar{r} R_e)^2 [\chi_2 \cos(\theta - \Omega) + \chi_1 \cos \theta], \end{aligned}$$

so :

$$6\mu R_e h_0 \omega \frac{\partial}{\partial \bar{r}} \left[\bar{r} \bar{h}^3 \frac{\partial \bar{p}}{\partial \bar{r}} \right] + 6\mu R_e h_0 \omega \frac{\partial}{\partial \theta} \left[\frac{\bar{h}^3}{\bar{r}} \frac{\partial \bar{p}}{\partial \theta} \right] = -6\mu R_e h_0 \omega \frac{R_e \chi_2}{h_0} \bar{r}^2 \left[\cos(\theta - \Omega) + \frac{\chi_1}{\chi_2} \cos \theta \right]$$

Divide with $6\mu R_e h_0 \omega$ and results the Reynolds equation in dimensionless measures.

$$\frac{\partial}{\partial \bar{r}} \left[\bar{r} \bar{h}^3 \frac{\partial \bar{p}}{\partial \bar{r}} \right] + \frac{\partial}{\partial \theta} \left[\frac{\bar{h}^3}{\bar{r}} \frac{\partial \bar{p}}{\partial \theta} \right] = -e_2 \bar{r}^2 [\cos(\theta - \Omega) + \chi \cos \theta] \quad (6)$$

2. THE INTEGRATION OF THE REYNOLDS EQUATION

For easing the notations, instead of $\bar{h}, \bar{r}, \bar{p}$ we will use r, h, p . Because $e_2 < 1$ (from $R_e(\chi_1 + \chi_2) < h_0$, so $e(1 + \chi) < 1$) a serial of powers are developed after e_2 the h și p functions.

We have:

$$\begin{aligned} h &= 1 + e_2 h_1(r, \theta), \text{ cu } h_1(r, \theta) = r [\sin(\theta - \Omega) - \chi \sin \theta] \\ p &= p_0(r, \theta) + e_2 p_1(r, \theta) + e_2^2 p_2(r, \theta) + \dots \end{aligned} \quad (7)$$

With (6) the equation (7) becomes

$$\frac{\partial}{\partial r} \left[r(1 + e_2 h_1)^3 \frac{\partial}{\partial r} \left(\sum_{k \geq 0} e_2^k p_k \right) \right] + \frac{\partial}{\partial \theta} \left[\frac{1}{r} (1 + e_2 h_1)^3 \frac{\partial}{\partial \theta} \left(\sum_{k \geq 0} e_2^k p_k \right) \right] = -e_2 r^2 [\cos(\theta - \Omega) + \chi \cos \theta]$$

$$\begin{aligned} & \frac{\partial [r(1 + e_2 h_1)^3]}{\partial r} \sum_{k \geq 0} e_2^k \frac{\partial p_k}{\partial r} + r(1 + e_2 h_1)^3 \sum_{k \geq 0} e_2^k \frac{\partial^2 p_k}{\partial r^2} + \\ & + \frac{1}{r} \frac{\partial [(1 + e_2 h_1)^3]}{\partial \theta} \sum_{k \geq 0} e_2^k \frac{\partial p_k}{\partial \theta} + \frac{1}{r} (1 + e_2 h_1)^3 \sum_{k \geq 0} e_2^k \frac{\partial^2 p_k}{\partial \theta^2} = -e_2 r^2 [\cos(\theta - \Omega) + \chi \cos \theta] \end{aligned}$$

or:

$$\begin{aligned} & \left[(1 + e_2 h_1)^3 + 3e_2 r(1 + e_2 h_1)^2 \frac{\partial h_1}{\partial r} \right] \sum_{k \geq 0} e_2^k \frac{\partial p_k}{\partial r} + r(1 + e_2 h_1)^3 \times \\ & \times \sum_{k \geq 0} e_2^k \frac{\partial^2 p_k}{\partial r^2} + \frac{3e_2}{r} (1 + e_2 h_1)^2 \frac{\partial h_1}{\partial \theta} \sum_{k \geq 0} e_2^k \frac{\partial p_k}{\partial \theta} + \frac{1}{r} (1 + e_2 h_1)^3 \times \\ & \times \sum_{k \geq 0} e_2^k \frac{\partial^2 p_k}{\partial \theta^2} = -e_2 r^2 [\cos(\theta - \Omega) + \chi \cos \theta] \end{aligned} \quad (8)$$

For identification of the e_2^k factors we get:

$$\text{For } e_2^0: \frac{\partial p_0}{\partial r} + r \frac{\partial^2 p_0}{\partial r^2} + \frac{1}{r} \frac{\partial^2 p_0}{\partial \theta^2} = 0.$$

The conditions $p_0(r, \theta) = p_0(1, \theta) = 0$ și $p_0(r, \theta) = p_0(r, \theta + 2\pi) = 0$

will get $p_0 = 0$.

For e^m , $m \geq 4$:

$$\begin{aligned} & \frac{\partial p_m}{\partial r} + \left[3h_1 + 3r \frac{\partial h_1}{\partial r} \right] \frac{\partial p_{m-1}}{\partial r} + \left[3h_1^2 + 6rh_1 \frac{\partial h_1}{\partial r} \right] \frac{\partial p_{m-2}}{\partial r} + \left[h_1^3 + 3rh_1^2 \frac{\partial h_1}{\partial r} \right] \frac{\partial p_{m-3}}{\partial r} + r \frac{\partial^2 p_m}{\partial r^2} + \\ & 3rh_1 \frac{\partial^2 p_{m-1}}{\partial r^2} + 3rh_1^2 \frac{\partial^2 p_{m-2}}{\partial r^2} + rh_1^3 \frac{\partial^2 p_{m-3}}{\partial r^2} + \frac{3}{r} \frac{\partial h_1}{\partial \theta} \frac{\partial p_{m-1}}{\partial \theta} + \frac{6}{r} h_1 \frac{\partial h_1}{\partial \theta} \frac{\partial p_{m-2}}{\partial \theta} + \frac{3}{r} h_1^2 \frac{\partial h_1}{\partial \theta} \frac{\partial p_{m-3}}{\partial \theta} + \\ & \frac{1}{r} \frac{\partial^2 p_m}{\partial \theta^2} + \frac{3h_1}{r} \frac{\partial^2 p_{m-1}}{\partial \theta^2} + \frac{3}{r} h_1^2 \frac{\partial^2 p_{m-2}}{\partial \theta^2} + \frac{1}{r} h_1^3 \frac{\partial^2 p_{m-3}}{\partial \theta^2} = 0 \end{aligned}$$

We take the equations:

$$r \frac{\partial^2 p_1}{\partial r^2} + \frac{1}{r} \frac{\partial^2 p_1}{\partial \theta^2} + \frac{\partial p_1}{\partial r} = -r^2 [\cos(\theta - \Omega) + \chi \cos \theta] \quad (9)$$

And respectively:

$$\begin{aligned} & r \frac{\partial^2 p_2}{\partial r^2} + \frac{1}{r} \frac{\partial^2 p_2}{\partial \theta^2} + \frac{\partial p_2}{\partial r} = \\ & - \left[3h_1 + 3r \frac{\partial h_1}{\partial r} \right] \frac{\partial p_1}{\partial r} - 3r h_1 \frac{\partial^2 p_1}{\partial r^2} - \frac{3}{r} \frac{\partial h_1}{\partial \theta} \frac{\partial p_1}{\partial \theta} - \frac{3}{r} h_1 \frac{\partial^2 p_1}{\partial \theta^2} \end{aligned} \quad (10)$$

Because $p(r, \theta) = p(r, \theta + 2\pi)$ it's expected that also $p_1(r, \theta) = p_1(r, \theta + 2\pi)$ so we can solve p_1 related to θ in a Fourier series, meaning:

$$p_1(r, \theta) = p_1^0(r) + \sum_{k \geq 1} [p_1^{ck}(r) \cos k\theta + p_1^{sk}(r) \sin k\theta] \quad (11)$$

We imply the equation solving (9)

$$p_1(r, \theta) = -\frac{1}{8} \left[r^3 - (r_i^2 + 1)r + r_i^2 \frac{1}{r} \right] [(\cos \Omega + \chi) \cos \theta + \sin \Omega \sin \theta] \quad (12)$$

For solving the (10) equation, because $p(r, \theta) = p(r, \theta + 2\pi)$ și $p_2(r, \theta) = p_2(r, \theta + 2\pi)$ we can develop p_2 related to θ in a Fourier series, meaning:

$$p_2(r, \theta) = p_2^0(r) + \sum_{k \geq 1} [p_2^{ck}(r) \cos k\theta + p_2^{sk}(r) \sin k\theta] \quad (13)$$

We introduce (13), (8)₁ and (9) în (10) and get:

$$\begin{aligned} & r \left[\frac{d^2 p_2^0}{dr^2} + \sum_{k \geq 1} \left(\frac{d^2 p_2^{ck}}{dr^2} \cos k\theta + \frac{d^2 p_2^{sk}}{dr^2} \sin k\theta \right) \right] - \frac{1}{r} \left[\sum_{k \geq 1} k^2 (p_2^{ck} \cos k\theta + p_2^{sk} \sin k\theta) \right] + \frac{dp_2^0}{dr} + \\ & \sum_{k \geq 1} \left[\frac{dp_2^{ck}}{dr} \cos k\theta + \frac{dp_2^{sk}}{dr} \sin k\theta \right] = \frac{6}{8} [r(\cos \Omega - \chi) \cos \theta - \sin \Omega \sin \theta] \left[3r^3 - (r_i^2 + 1)r - r_i^2 \frac{1}{r^2} \right] \\ & [(\cos \Omega + \chi) \cos \theta + \sin \Omega \sin \theta] + \frac{3}{8} r [r(\cos \Omega - \chi) \sin \theta - \sin \Omega \cos \theta] \left[6r + r_i^2 \frac{1}{r^2} \right] \\ & [(\cos \Omega + \chi) \cos \theta + \sin \Omega \sin \theta] + \\ & \frac{3}{8} \frac{1}{r} [r(\cos \Omega - \chi) \sin \theta - \sin \Omega \cos \theta] \left[r^3 - (r_i^2 + 1)r + r_i^2 \frac{1}{r} \right] [(-\cos \Omega + \chi) \sin \theta + \sin \Omega \sin \theta] + \end{aligned}$$

$$\frac{3}{8}r \left[r(\cos \Omega - \chi) \sin \theta - \sin \Omega \cos \theta \right] \left[r^3 - (r_i^2 + 1)r + r_i^2 \frac{1}{r} \right] \left[(-\cos \Omega + \chi) \cos \theta + \sin \Omega \sin \theta \right]$$

The (14) connection is implied

$$\begin{aligned} p_2(r, \theta) &= p_2^0(r) + p_2^{c2}(r) \cos 2\theta + p_2^{s2}(r) \sin 2\theta = \\ &+ 2(r_i^2 + 1)r^2 - 3r^4 \Big] + \frac{3}{32} \chi \sin \Omega \left[1 - 2r_i^2 + (r_i^4 - 1) \frac{\ln r}{\ln r_i} + \frac{1}{32} \sin 2\Omega \right. \\ &\left[\frac{5 + 8r_i^2 + 5r_i^4}{1 + r_i^2} r^2 - 2 \frac{r_i^4}{1 + r_i^2} \frac{1}{r^2} - 3r_i^2 - 5r_i^4 \right] \cos 2\theta + \\ &\left. + \frac{1}{32} (\cos 2\Omega - \chi^2) \left[-\frac{5 + 8r_i^2 + 5r_i^4}{1 + r_i^2} r^2 + 2 \frac{r_i^4}{1 + r_i^2} \frac{1}{r^2} + 3r_i^2 + 5r_i^4 \right] \sin 2\theta. \right. \end{aligned} \quad (14)$$

From (8), (12) and (14) it results (15):

$$\begin{aligned} p(r, \theta) &= e_2 p_1(r, \theta) + e_2^2 p_2(r, \theta) = -\frac{e_2}{8} \left[r^3 - (r_i^2 + 1)r + \frac{r_i^2}{r} \right] \\ &\left[(\cos \Omega + \chi) \cos \theta - \sin \Omega \sin \theta \right] + \\ &+ \frac{e_2^2}{32} \left\{ \chi \sin \Omega \left[1 - 2r_i^2 + (r_i^4 - 1) \frac{\ln r}{\ln r_i} + 2(r_i^2 + 1)r^2 - 3r^4 \right] + \right. \\ &\left[\sin 2\Omega \cos 2\Omega - (\cos 2\Omega - \chi^2) \sin 2\theta \right] \times \\ &\times \left[\frac{5 + 8r_i^2 + 5r_i^4}{1 + r_i^2} r^2 - 2 \frac{r_i^4}{1 + r_i^2} \frac{1}{r^2} - 3r_i^2 - 5r_i^4 \right] \Big\}. \end{aligned} \quad (15)$$

We come again to the notations $\bar{p}, \bar{r}, \bar{r}_i$ and get the film pressure as (16):

$$\begin{aligned} \bar{p}(\bar{r}, \theta) &= -\frac{e_2}{8} \left[\bar{r}^3 - (\bar{r}_i^2 + 1)\bar{r} + \frac{\bar{r}_i^2}{\bar{r}} \right] \left[(\cos \Omega + \chi) \cos \theta - \sin \Omega \sin \theta \right] + \\ &+ \frac{e_2^2}{32} \left\{ \chi \sin \Omega \left[1 - 2\bar{r}_i^2 + (\bar{r}_i^4 - 1) \frac{\ln \bar{r}}{\ln \bar{r}_i} + 2(\bar{r}_i^2 + 1)\bar{r}^2 - 3\bar{r}^4 \right] \right. \\ &+ \left[\sin 2\Omega \cos 2\Omega - (\cos 2\Omega - \chi^2) \sin 2\theta \right] \\ &\left. \left[\frac{5 + 8\bar{r}_i^2 + 5\bar{r}_i^4}{1 + \bar{r}_i^2} \bar{r}^2 - 2 \frac{\bar{r}_i^4}{1 + \bar{r}_i^2} \frac{1}{\bar{r}^2} - 3\bar{r}_i^2 - 5\bar{r}_i^4 \right] \right\}. \end{aligned} \quad (16)$$

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